Bayesian Principles for Learning Machines

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Al that learn like humans

Learn and adapt quickly throughout their lives

Human Learning at the age of 6 months.



Converged at the age of 12 months



Transfer skills at the age of 14 months



Bayesian Principles





Human learning



Deep learning

Life-long learning from small chunks of data in a non-stationary world

Bulk learning from a large amount of data in a stationary world

My current research focuses on reducing this gap!

- 1. Parisi, German I., et al. "Continual lifelong learning with neural networks: A review." *Neural Networks* (2019)
- 2. Geisler, W. S., and Randy L. D. "Bayesian natural selection and the evolution of perceptual systems." *Philosophical Transactions of the Royal Society of London. Biological Sciences* (2002)

Bayesian (Principles for) Learning Machines

- Bayes is essential for human-like learning, but infeasible
- Principle I: Bayes Learning Rule (estimation)
- Principle II: Bayes dual (explore-exploit)
- The way forward to human-like learning
- Disclaimer: Focus on the concepts rather than the details

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Principle of Trial-and-Error

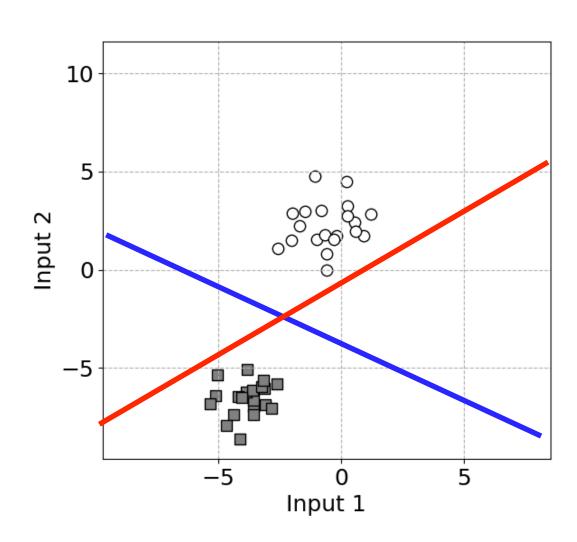
Frequentist: Empirical Risk Minimization (ERM) or Maximum Likelihood Principle, etc.

$$\min_{\theta \text{ Loss}} \ell(\mathcal{D}, \theta) = \sum_{i=1}^{N} [y_i - f_{\theta}(x_i)]^2 + \gamma \theta^T \theta$$
 $\max_{\theta \text{ Deep}} \ell(\mathcal{D}, \theta) = \sum_{i=1}^{N} [y_i - f_{\theta}(x_i)]^2 + \gamma \theta^T \theta$
Model Params

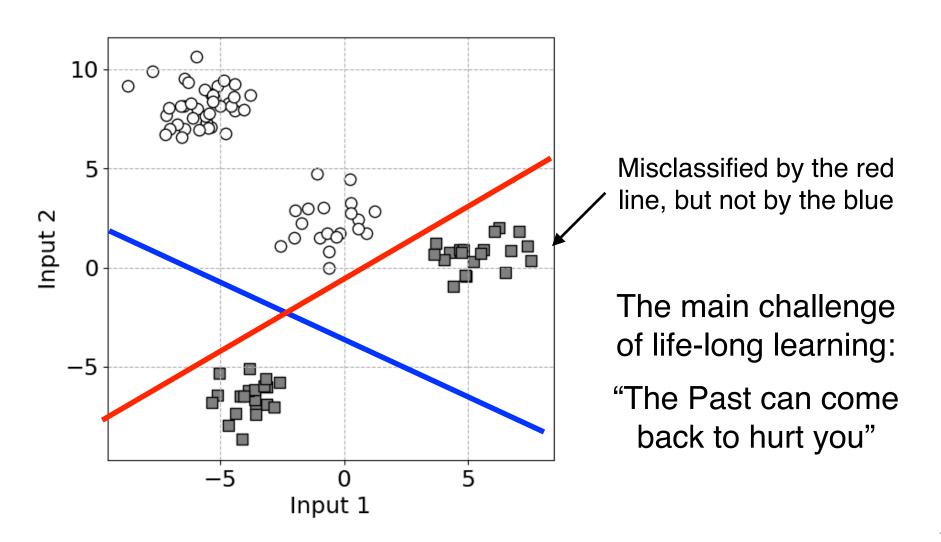
Deep Learning Algorithms: $\theta \leftarrow \theta - \rho H_{\theta}^{-1} \nabla_{\theta} \ell(\theta)$

Scales well to large data and complex model, and very good performance in practice.

Which is a good classifier?



Which is a good classifier?

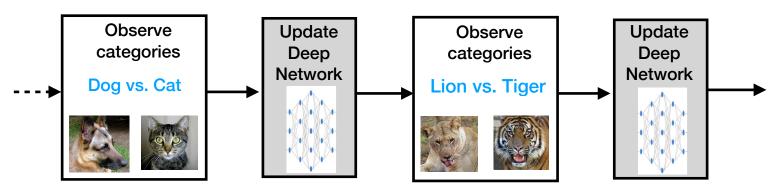


Life-Long Deep Learning?

Standard Deep Learning



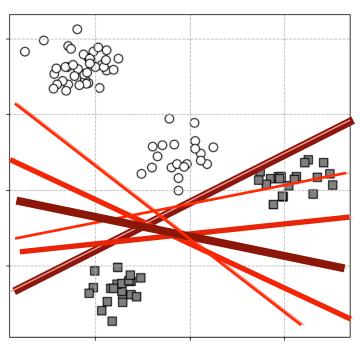
Continual Learning: past classes never revisited



Standard deep learning forgets the past data.

Kirkpatrick, James, et al. "Overcoming catastrophic forgetting in neural networks." *Proceedings of the national academy of sciences* 114.13 (2017): 3521-3526.

Bayesian Principles



(1) Keep your options open

$$p(\theta|\mathcal{D}_1) = \frac{p(\mathcal{D}_1|\theta)p(\theta)}{\int p(\mathcal{D}_1|\theta)p(\theta)d\theta}$$

(2) Revise with new evidence

$$p(\theta|\mathcal{D}_2, \mathcal{D}_1) = \frac{p(\mathcal{D}_2|\theta)p(\theta|\mathcal{D}_1)}{\int p(\mathcal{D}_2|\theta)p(\theta|\mathcal{D}_1)d\theta}$$

Similar ideas in sequential/online decision-making (uncertainty/randomization). Computation is infeasible.

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Learning-Algorithms from Bayes

Approximate Bayes with the Bayesian learning rule Posterior Approximation <=> Learning-Algorithm



of Newton

Bayesian Learning Rule

Entropy

$$\min_{\theta} \ \ell(\theta) \quad \text{vs} \quad \min_{q \in \mathcal{Q}} \mathbb{E}_{\textcolor{red}{q(\theta)}}[\ell(\theta)] - \mathcal{H}(q)$$
 Exponential-family Approx.

Deep Learning algo:
$$\theta \leftarrow \theta - \rho H_{\theta}^{-1} \nabla_{\theta} \ell(\theta)$$

Bayes learning rule:
$$\lambda \leftarrow \lambda - \rho \nabla_{\mu} \left(\mathbb{E}_q[\ell(\theta)] - \mathcal{H}(q) \right)$$

Natural Gradient

Natural and Expectation parameters of an exponential family distribution q

Deep Learning algorithms can be obtained by

- 1. Choosing a Gaussian approximation,
- 2. Giving away the "global" property of the rule

^{1.} Khan and Lin. "Conjugate-computation variational inference: Converting variational inference in non-conjugate models to inferences in conjugate models." Alstats (2017).

Bayesian learning rule: $\lambda \leftarrow \lambda - \rho \nabla_{\mu} (\mathbb{E}_q[\ell(\theta)] - \mathcal{H}(q))$

Learning Algorithm	Posterior Approx.	Algorithmic Approx.	Sec.
Optimization Algorithms			
Gradient Descent	Gaussian (fixed cov.)	Delta approx.	1.4
Newton's method	Gaussian		1.4
$Multimodel\ optimization\ {\scriptstyle (New)}$	Mixture of Gaussians		3.2
Deep-Learning Algorithms			
Stochastic Gradient Descent	Gaussian (fixed cov.)	Delta approx., Stochastic approx.	4.1
RMSprop/Adam	Gaussian (diagonal cov.)	Delta approx., Stochastic approx., Hessian approx., Square-root scaling, Slow-moving scale vectors	4.2, 4.3
Dropout	Mixture of Gaussians	Delta approx., Stochastic approx., Responsibility approx.	4.4
STE	Bernoulli	Delta approx., Stochastic approx.	4.6
Online Gauss-Newton (OGN) (New)	Gaussian (diagonal cov.)	Gauss-Newton Hessian approx. in Adam & no square-root scaling	4.5
Variational OGN (New)	"	Remove Delta approx. from OGN	4.5
Bayesian Binary NN (New)	"	Remove Delta approx. from STE	4.6
Approximate Bayesian Inference Algorithms			
Conjugate Bayes	Exp-family	Set learning rate $\rho_t = 1$	5.1
Laplace's method	Gaussian	Delta approx.	5.2
Expectation-Maximization	${\it Exp-Family} + {\it Gaussian}$	Delta approx. for the parameters	5.3
Stochastic VI (SVI)	Exp-family (mean-field)	Stochastic approx., local rate $\rho_t=1$	5.4
VMP		Set learning rate $\rho_t = 1$	5.4
Non-Conjugate VMP	"	"	5.4
Non-Conjugate VI (New)	Mixture of Exp-family	None	5.5

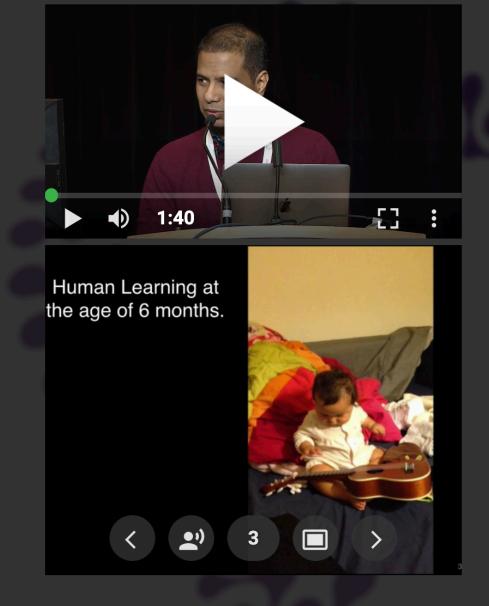
Khan and Rue. "Learning-Algorithms from Bayesian Principles" (2020)

Work in progress (draft available at https://emtiyaz.github.io/papers/learning from bayes.pdf)

We can design new algorithms by relaxing the approximations.

For example, to estimate uncertainty via Adam, we can put back the expectation wrt q. This gives us the VOGN algorithm.

- 1. Khan, et al. "Fast and scalable Bayesian deep learning by weight-perturbation in Adam." *ICML* (2018).
- 2. Osawa et al. "Practical Deep Learning with Bayesian Principles." NeurIPS (2019).



Deep Learning with Bayesian Principles

by Mohammad Emtiyaz Khan · Dec 9, 2019

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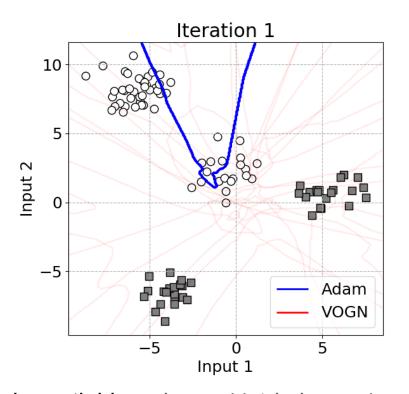
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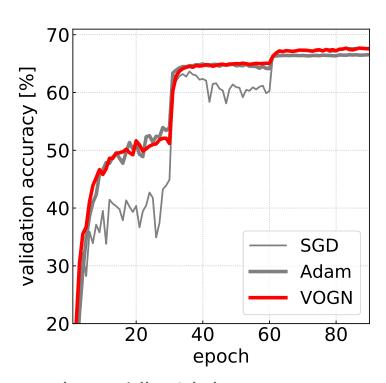
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Uncertainty Estimation in DL

VOGN: A modification of Adam but match the performance on ImageNet



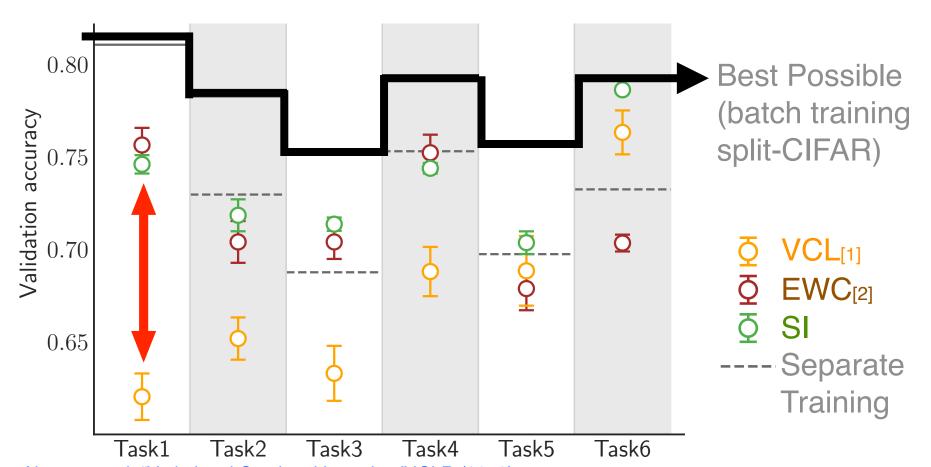


Code available at https://github.com/team-approx-bayes/dl-with-bayes

- 1. Khan, et al. "Fast and scalable Bayesian deep learning by weight-perturbation in Adam." *ICML* (2018).
- 2. Osawa et al. "Practical Deep Learning with Bayesian Principles." NeurIPS (2019).

Continual Learning: Fixing Bayes

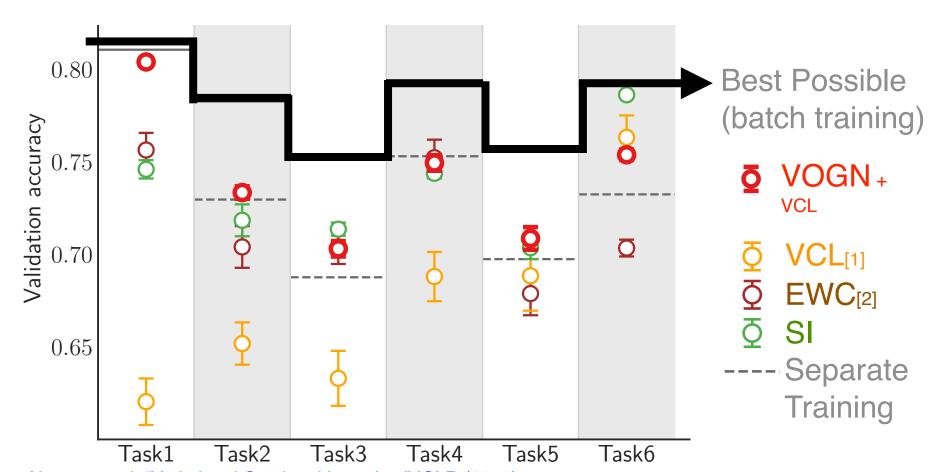
VCL is Bayesian method, trained using SGD, & performs poorly



- 1. Nguyen et al. "Variational Continual Learning." ICLR (2018).
- 2. Kirkpatrick, James, et al. "Overcoming catastrophic forgetting in neural networks." PNAS 2017

Continual Learning: Fixing Bayes

Bayesian Learning Rule (VOGN) fixes the gap



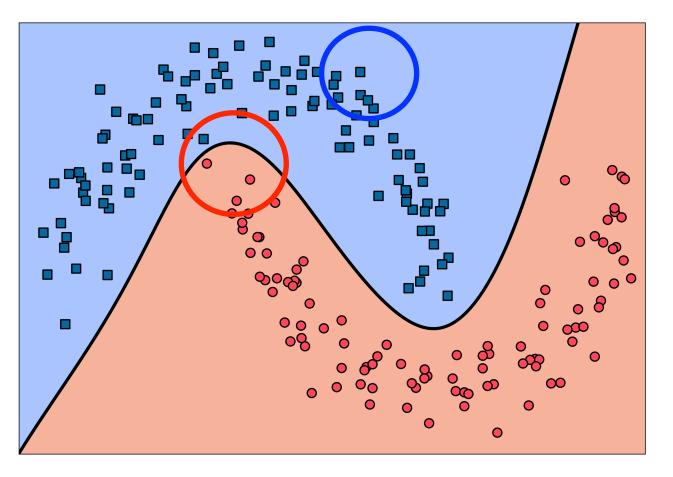
- 1. Nguyen et al. "Variational Continual Learning." ICLR (2018).
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Bayesian (Principles for) Learning Machines

- Bayes is essential for human-like learning, but infeasible
- Principle I: Bayes Learning Rule (estimation)
 - Unify, generalize, and improve learning-algorithms
 - Application: Uncertainty estimation in deep learning
- Principle II: Bayes dual (explore-exploit)
 - Knowledge transfer using a dual representation
 - Application: Continual learning of deep networks
- The way forward to human-like learning
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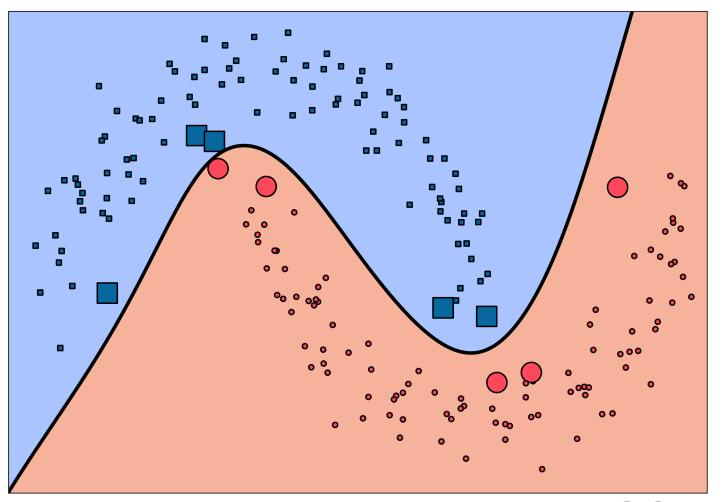
Relevance of Data Examples

Which examples are most relevant for the classifier? Red circle vs Blue circle.



Model view vs Data view

Bayes "automatically" defines data-relevance



Data view (Very much like SVMs)

Bayes Duality

 DNN2GP: Gaussian approx fom Bayes learning rule connect NN to Linear models & Gaussian Process (GPs) [1].

$$\sum_{i=1}^{N} \ell(y_i, f_{\theta}(x_i)) \approx \sum_{i=1}^{N} \frac{1}{\sigma_i^2} [\tilde{y}_i - \phi_i(x_i)^{\top} \theta]^2$$
neural network

"Dual" variables obtained from $\nabla_{\mu}\mathbb{E}_{q}[\ell_{i}(\theta)]$ (For Gaussian approx, obtained from Jacobian, residual etc.)

- sigma_i^2 defines the "relevance" of the data examples. We call more relevant ones the "memorable examples".
- Natural-gradients give "dual variables" (Bayes Duality)

Least Relevant

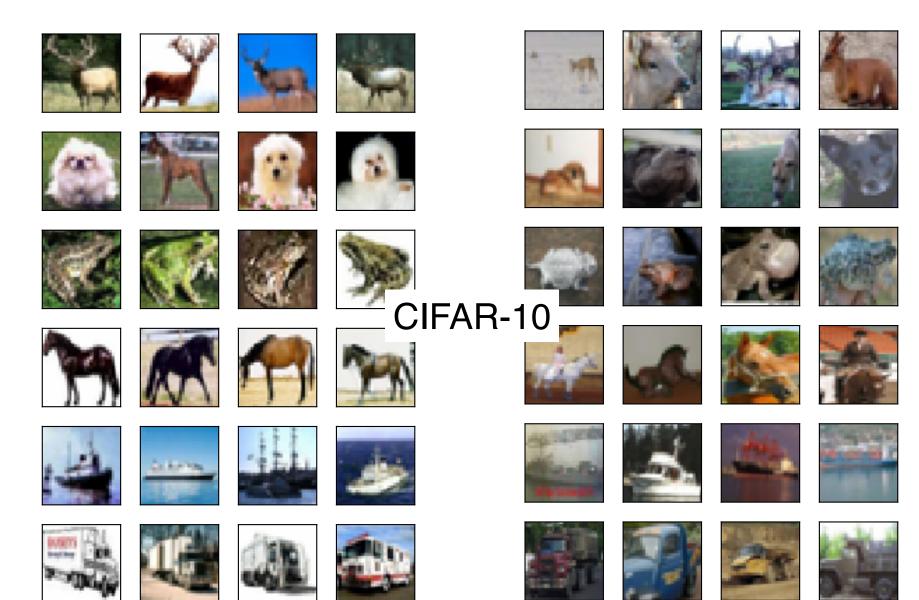
Most Relevant



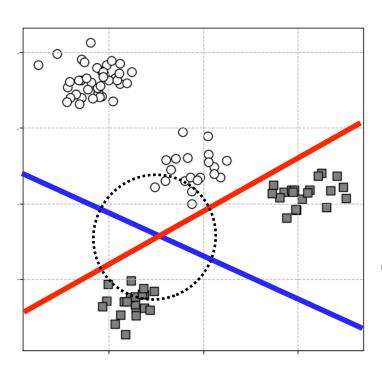


Least Relevant

Most Relevant



Continual Learning with Bayes Dual



Before: Use past posterior as prior for the next task

$$p(\theta|\mathcal{D}_2, \mathcal{D}_1) = \frac{p(\mathcal{D}_2|\theta)p(\theta|\mathcal{D}_1)}{\int p(\mathcal{D}_2|\theta)p(\theta|\mathcal{D}_1)d\theta}$$

Gauss Approx (Weight regularization [1])

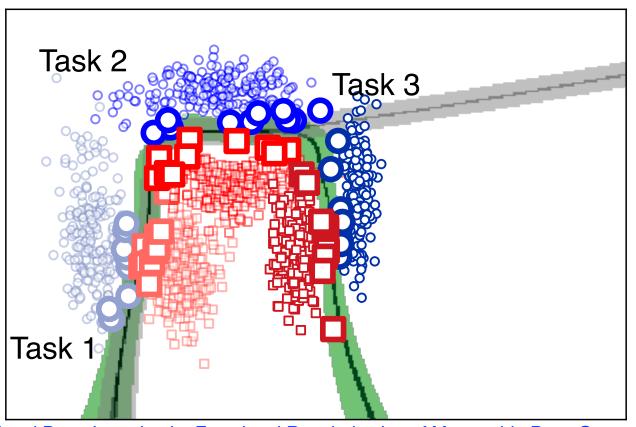
$$(\boldsymbol{\theta} - \boldsymbol{\theta}_{old})^{\mathsf{T}} \Sigma_{old}^{-1} (\boldsymbol{\theta} - \boldsymbol{\theta}_{old})$$

New Idea: Don't let the predictions of memorable examples change (functional regularization with GPs)

$$\left[f(X_m) - f_{old}(X_m)\right]^{\mathsf{T}} K_{old}(X_m, X_m)^{-1} \left[f(X_m) - f_{old}(X_m)\right]$$

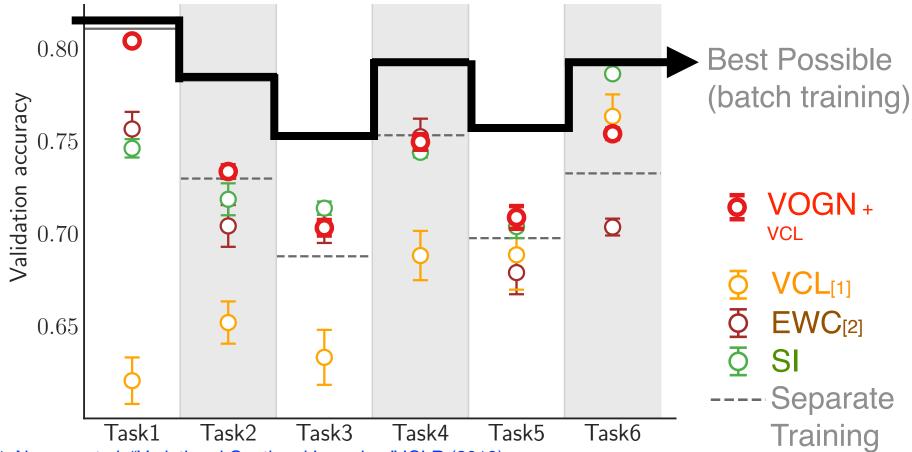
Functional Regularization of Memorable Past (FROMP)

Regularize the function outputs. Simply adds an additional term in Adam.



Continual Learning: Improving Bayes

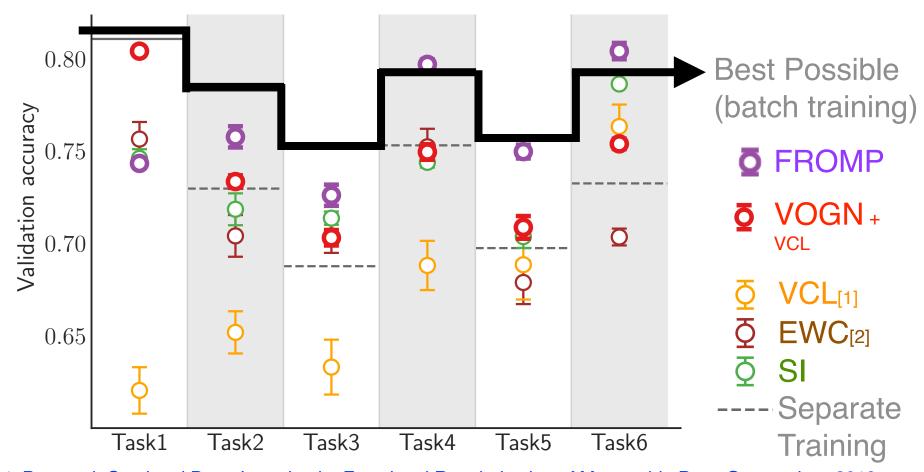
VOGN uses Gaussian posterior as prior in "weight-space", does not perform significantly better than other methods



- 1. Nguyen et al. "Variational Continual Learning." ICLR (2018).
- 2. Kirkpatrick, James, et al. "Overcoming catastrophic forgetting in neural networks." PNAS 2017

Continual Learning: Improving Bayes

FROMP uses a GP prior in "function-space" over the "memorable pasts" and improves the performance.



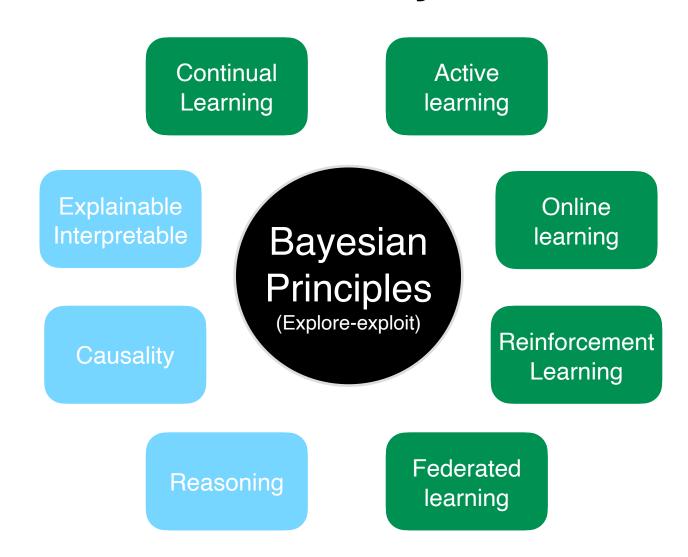
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Human Learning at the age of 6 months.



Bayes is indispensable for an Al that learns as efficiently as we do



How to design AI that learn like us?

- Three questions
 - Q1: What do we know? (model)
 - Q2: What do we not know? (uncertainty)
 - Q3: What do we need to know? (action & exploration)
- Posterior approximation is the key
 - (Q1) Models == representation of the world
 - (Q2) Posterior approximations == representation of the model
 - (Q3) The Bayes-dual representation will enable
 - represent learned knowledge,
 - reuse them in novel situations,
 - interact with the environment to collect new knowledge

Learning-Algorithms from Bayesian Principles

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> Version of November 3, 2020 DRAFT ONLY



Abstract

We show that many machine-learning algorithms are specific instances of a *single* algorithm called the Bayesian learning rule. The rule, derived from Bayesian principles, yields a wide-range of algorithms from fields such as optimization, deep learning, and graphical models. This includes classical algorithms such as ridge regression, Newton's method, and Kalman filter, as well as modern deep-learning algorithms such as stochastic-gradient descent, RMSprop, Adam, and Dropout. The key idea is to estimate posterior approximations using the Bayesian learning rule. Different approximations then result in different algorithms and further algorithmic approximations give rise to variants of those algorithms. Our work shows that Bayesian principles not only unify, generalize, and improve existing learning-algorithms, but also help us design new ones.

Available at

https://emtiyaz.github.io/papers/learning_from_bayes.pdf

Acknowledgements

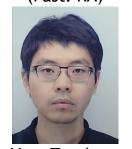
Slides, papers, & code are at emtiyaz.github.io



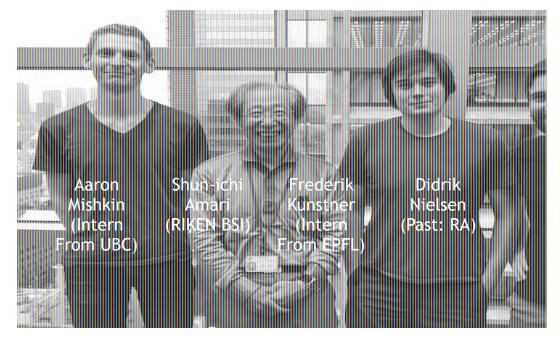
Wu Lin (Past: RA)



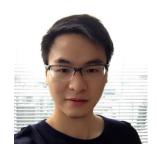
Nicolas Hubacher (Past: RA)



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Slides, papers, & code are at emtiyaz.github.io



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Emtiyaz Khan Team Leader



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Gian Maria Marconi Postdoc



Thomas Möllenhoff
Postdoc



Open post-doc/RA position: https://www.riken.jp/en/ careers/researchers/ 20201022 2/index.html



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